Rheological Characterization of Director Dynamics in a Nematic Monodomain Containing Mesogenic Polymers of Differing Architectures

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ABSTRACT: The rheological behavior of dilute nematic mixtures containing liquid crystal polymers (LCP) with different molecular architectures dissolved in low molar mass nematogens is investigated. Addition of a side-chain LCP (MSHMA) to a flow-aligning nematic solvent, pentylcyanobiphenyl (5CB), alters the rheology to director-tumbling character. Conversely, dissolution of a main-chain LCP (TPB-15) in a director-tumbling nematic, octylcyanobiphenyl (8CB), suppresses the tumbling behavior and produces a flow-aligning response. A characteristic pattern of shear stress oscillations is observed for MSHMA/5CB mixtures and pure 8CB, indicative of director tumbling, in flow startup, step flow, and flow reversal experiments. In contrast, TPB-15/8CB and TPB-15/5CB mixtures show no oscillatory response but a single stress overshoot, characteristic of a flow-aligning nematic such as pure 5CB. Concentration and temperature dependences of the rheological effect of LCP are presented. Our results demonstrate that addition of sufficient amounts of LCP to a nematic solvent can change the sign of the Leslie viscosity coefficient α_3 . Our findings are qualitatively consistent with a theoretical model of Brochard (1979), provided that the side-chain LCP has an oblate molecular configuration, while the main-chain LCP maintains a prolate molecular configuration in the nematic solvent. Analysis of the transient shear response function via the Erickson-Leslie-Parodi formalism yields viscosity coefficients of the mixtures and hence an estimate of the effective axial ratio of the polymer chain.

1. Introduction

When a nematic liquid crystal monodomain is subjected to a shear flow, the orientational response of the nematic director depends on the six Leslie viscosity coefficients α_1 - α_6 and the three Frank elastic constants K_{11} - K_{33} . In particular, nematics can be divided into two classes according to the sign of the coefficient α_3 , given that the coefficient α_2 is generally negative. The first class, comprising materials with $\alpha_3 < 0$, will shear-align, with the director at a characteristic angle with respect to the flow direction in a simple shear field. The second class are materials with $\alpha_3 > 0$, for which the director is forced to rotate by the hydrodynamic torques in a simple shear flow. The former is referred to as "flow aligning" and the latter as "tumbling", respectively. For low molar mass nematics (LMMN), director tumbling is not a common rheological phenomenon. For a few LMMN, such as p-(nhexyloxy)benzilidene-p'-aminobenzonitrile (HBAB) and octylcyanobiphenyl (8CB), α_3 has been reported positive and director-tumbling behavior has been clearly demonstrated.3-7

In recent years, many efforts have been made to understand and modify the rheological behavior of polymer liquid crystalline solutions and melts, with a view to obtaining optimal physical properties of the processed materials. There have been experimental reports identifying pronounced oscillations of both shear stress and optical response, in the rheological behavior of liquid crystal polymers (LCP) solutions and melts. Systems studied include lyotropic nematic solutions of poly(benzyl glutamate) (PBG),8-13 (hydroxylpropyl)cellulose (HPC),14 poly(p-phenylenebenzobisthiazole) (PBZT),15 poly(n-hexyl isocyanate) (PHIC),16,17 and thermotropic copolyester nematic melts in transient shear flow.118-19 Theoretical analysis suggests that these oscillations are due to director tumbling.17,18,20,21 The explanation for the stress oscilla-

tions is that when the shear flow starts at a high enough shear rate, the director will rotate through several multiples of π under the influence of the hydrodynamic torque coupled to the director; thus, the transient shear stress exhibits a series of extrema which correspond to certain angles of director orientation. The characteristics of the stress oscillation, such as amplitude, frequency, and relaxation rate, depend on the initial director orientation state, the shear rate, and, most importantly, on the viscoelastic properties of the nematic. The rheology of LCP solutions and melts is complicated by the fact that the coupling between the nematic director and the polymer chain makes it difficult for the director to avoid hydrodynamic torques. Moreover, the flexibility of the backbone and/or spacer, the configurational anisotropy, and the high density of defects or the polydomain structure generate additional complexity.

Here we are interested in the rheological behavior of dilute nematic solutions of LCP in low molar mass nematogens (LCP/LMMN mixtures). By using nematic monodomains, we avoid the problem of high defect density in characterizing the rheological behavior. Also, as we shall see, a molecular hydrodynamic formulation of liquid crystal rheology in terms of LCP chain configuration is simpler in dilute than in concentrated systems. When a small amount of a liquid crystal polymer is dissolved into a nematic solvent, a large change in the rheological behavior of the mixture may be expected, since the polymer chain occupies a large hydrodynamic volume fraction in the nematic medium. In addition, the interaction between the anisotropic solvent and the mesogenic groups in a liquid crystal polymer can make the polymer backbone configuration highly nonspherical. This configurational anisotropy has been observed directly via small-angle scattering experiments for side-chain and main-chain liquid crystal polymers in low molar mass nematic solvents. 22,23 For main-chain LCP, the chain configuration is generally prolate with the long axis parallel to the nematic director; for side-chain LCP, prolate or oblate configurations may

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be found, depending on backbone flexibility and spacer length. A theoretical analysis of the viscosity increments due to the dissolution of flexible polymer chains in a nematic fluid has been described by Brochard,²⁴ who developed expressions in terms of a few microscopic parameters such as R_{\perp} , R_{\parallel} (the radii of gyration of polymer chains perpendicular and parallel to the director), and the configurational relaxation time of the chain τ_R :

$$\delta \gamma_1 = (ckT/N)\tau_R (R_{\perp}^2 - R_{\parallel}^2)^2 / R_{\perp}^2 R_{\parallel}^2 \tag{1}$$

$$\delta \gamma_2 = (ckT/N)\tau_R (R_{\perp}^4 - R_{\parallel}^4)/R_{\perp}^2 R_{\parallel}^2$$
 (2)

$$\delta \eta_{\rm b} = (ckT/N)\tau_{\rm R}(R_{\perp}^2/R_{\parallel}^2) \tag{3}$$

Application of the relations $\alpha_2 = (\gamma_2 - \gamma_1)/2$ and $\alpha_3 = (\gamma_1 + \gamma_2)/2$ to eqs 1 and 2 yields directly

$$\delta \alpha_2 = (ckT/N)\tau_{\rm R}(R_{\perp}^2 - R_{\parallel}^2)/R_{\perp}^2 \tag{4}$$

$$\delta \alpha_3 = (ckT/N)\tau_R(R_{\perp}^2 - R_{\parallel}^2)/R_{\parallel}^2$$
 (5)

Here γ_1 is the twist viscosity, η_b is one of the Miesowicz viscosities, c is the concentration, k is Boltzmann's constant, T is the absolute temperature, and N is the degree of polymerization. According to eqs 1-5, the incremental changes on addition of polymer for the various viscosity coefficients are numerically different and depend strongly on the anisotropic ratio R_{\perp}/R_{\parallel} . Note that, as indicated by eq 5, addition of an oblate LCP results in a positive increment to α_3 , whereas addition of a prolate LCP gives a negative increment. This implies that a flow-aligning low molar mass nematic can be converted to a directortumbling system simply by dissolution of a sufficient quantity of a side-chain liquid crystal polymer which has an oblate configuration, and a director-tumbling low molar mass nematic can be turned into a flow-aligning system by adding a main-chain liquid crystal polymer which has a prolate configuration. Also, because α_3 is usually small in amplitude for low molar mass nematics, this distinctive change in rheological behavior can be achieved at very low polymer concentrations.

In previous studies, 25-27 we have investigated the changes in the viscosity and elastic coefficients of nematic mixtures of 5CB with certain side-chain and main-chain liquid crystal polymers using dynamic light scattering and Freedericksz transition techniques. Our results suggest that the backbone of the side-chain liquid crystal polymers takes an oblate configuration, that is, $R_{\perp}/R_{\parallel} > 1$. On the other hand, a prolate configuration, that is, $R_{\perp}/R_{\parallel} < 1$, was deduced for the main-chain liquid crystal polymers. However, dynamic light scattering measurements cannot unambiguously determine the sign of α_3 , since the relaxation time for the splay deformation mode, in which α_3 appears, is insensitive to the sign of α_3 .²⁵ Furthermore, since the magnitude of α_3 for low molar mass nematics is always much smaller than that of the other viscosity coefficients, such as α_2 , γ_1 , and η_b , which contribute to the relaxation times measured in dynamic light scattering, the contributions from α_3 are smaller than the experimental error. Therefore, a more sensitive method such as direct rheological or rheooptical investigation is required to determine the sign and magnitude of α_3 .

Following the linear nematohydrodynamic formalism of Erickson, Leslie, and Parodi (ELP), ^{28–30} a characteristic oscillating response of the shear stress is predicted for a material which exhibits director tumbling, whereas an initial stress overshoot followed by a steady shear stress value is predicted for a flow-aligning nematic. According to Erickson's transversely isotropic fluid model which

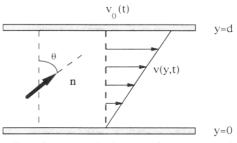


Figure 1. Two-dimensional schematic description of shear flow for a nematic monodomain.

neglects elasticity, 28 the stress tensor τ is

$$\tau = 2\mu \mathbf{D} + 2\mu_1 \mathbf{D} \cdot \hat{n} \hat{n} \hat{n} \hat{n} + 2\mu_2 (\hat{n} \hat{n} \cdot \mathbf{D} + \mathbf{D} \cdot \hat{n} \hat{n})$$
 (6)

and the director evolution equation becomes

$$\partial \hat{n}/\partial t = \hat{n} \cdot \Omega + \lambda (\hat{n} \cdot \mathbf{D} - \mathbf{D} : \hat{n} \hat{n} \hat{n})$$
 (7)

where \hat{n} is the unit vector identifying the nematic director, **D** is the rate of deformation tensor, Ω is the vorticity tensor, and the parameters μ , μ_1 , μ_2 , and λ are functions of the Leslie coefficients²⁹

$$\lambda = \frac{\alpha_5 - \alpha_6}{\alpha_3 - \alpha_2} \tag{8}$$

$$\mu = \alpha_A/2 \tag{9}$$

$$\mu_1 = \frac{\alpha_1}{2} - \frac{(\alpha_2 + \alpha_3)(\alpha_6 - \alpha_5)}{2(\alpha_2 - \alpha_3)}$$
 (10)

$$\mu_2 = \frac{\alpha_2 \alpha_6 - \alpha_3 \alpha_5}{\alpha_2 - \alpha_3} \tag{11}$$

Considering a two-dimensional system, as shown in Figure 1, we have $n_x = \sin \theta$, $n_y = \cos \theta$, $n_z = 0$, $D_{ij} = \omega_{ij} = 0$, except $D_{xy} = D_{yx} = \omega_{xy} = -\omega_{yx} = \gamma/2$ (γ is the velocity gradient or shear rate). Using relationships $\alpha_2 + \alpha_3 = \alpha_6 - \alpha_5^{30}$ and $\eta_b = (\alpha_3 + \alpha_4 + \alpha_6)/2$, if from eq 6, we obtain

$$\tau_{xy} = \dot{\gamma} \left\{ \left[\alpha_1 + \frac{(\alpha_2 + \alpha_3)^2}{\alpha_3 - \alpha_2} \right] \sin^2 \theta \cos^2 \theta + \eta_b - \frac{\alpha_3^2}{\alpha_3 - \alpha_2} \right\} = \frac{1}{\gamma \eta_{\text{max}}}$$

and from eq 7, we have

$$\frac{\partial \theta}{\partial t} = \frac{(\alpha_3 \sin^2 \theta - \alpha_2 \cos^2 \theta)}{\alpha_3 - \alpha_2} \dot{\gamma} \tag{13}$$

where $\eta_{\rm app}$ is the apparent viscosity. The distinctive difference between flow-aligning and director-tumbling behavior is implicitly contained in eq 13. Noting that α_2 is always negative, integration over eq 13 gives

$$\tan \theta = \left(\frac{-\alpha_2}{\alpha_3}\right)^{1/2} \tan \left[\frac{(-\alpha_2 \alpha_3)^{1/2}}{\alpha_3 - \alpha_2} \gamma\right] \qquad \text{for } \alpha_3 > 0 \quad (14)$$

and

$$\tan \theta = \left(\frac{\alpha_2}{\alpha_3}\right)^{1/2} \tanh \left[\frac{(\alpha_2 \alpha_3)^{1/2}}{\alpha_3 - \alpha_2} \gamma\right] \qquad \text{for } \alpha_3 < 0$$
(15)

As indicated by eq 14, for $\alpha_3 > 0$, the director rotation angle θ will always increase with strain and an indefinite oscillatory response is predicted, resembling the behavior of a single fiber tumbling in a shear flow (a Jeffery orbit). In contrast, since $\tanh(x) \rightarrow 1$ as $x \gg 1$, eq 15 predicts flow-aligning behavior since a maximum director rotation angle is reached at $\theta = \tan^{-1}[(\alpha_1/\alpha_3)^{1/2}]$ when the strain γ is large enough. According to eqs 12, 14, and 15, the apparent viscosity η_{app} is a function of the director rotation

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angle which changes with shear strain. By taking first and second derivatives of $\eta_{\rm app}$ with respect to θ , it is easy to show that a single maximum appears in $\eta_{\rm app}$ at $\theta=\pi/4$ for a flow-aligning nematic, while for a director-tumbling system, a series of maxima are present in $\eta_{\rm app}$ at $\theta=m\pi/4$ $(m={\rm odd})$, and a series of minima are present at $\theta=n\pi/2$ $(n=0,1,2,3,...),^{17,18}$ provided that

$$\alpha_1 > -\left[\frac{(\alpha_2 + \alpha_3)^2}{\alpha_3 - \alpha_2}\right] \tag{16}$$

This inequality is generally true for low molar mass nematic materials. 32

The applicability of the 2D Erickson transversely isotropic fluid model to depict the transient shear response of tumbling nematics is limited in the event that the director moves out of the shear plane (out-of-plane instability). Such out-of-plane motion has been shown theoretically and experimentally to occur at relatively small Erickson numbers (ratios of hydrodynamic to elastic forces) of 20–40.^{33,34} However, tumbling has also been observed without an out-of-plane instability in a torsional parallel-plate flow experiment.³⁵ It was proposed by Carlson² that a pressure drop induced by a hydrodynamic back flow³⁶ tends to keep the director in the shear plane.

Recently, we examined the transient shear flow response of a homeotropic monodomain formed from a nematic mixture of 5CB with a side-chain LCP, poly[6-(4-methoxy- α -methylstilben-4'-yl)oxy]hexyl methacrylate] (MSH-MA), at a polymer concentration of 4.5% w/w and compared this response to that of pure 5CB and pure 8CB.³⁷ Since pure 5CB is known to have negative α_3 and negative α_2 over its entire nematic range and since pure 8CB is a material with a positive α_3 over a major part of its nematic range, these two low molar mass nematics provide us respectively with reference examples of flowaligning and tumbling systems. We found that, on addition of MSHMA to the nematic solvent 5CB, the shear flow character was altered from flow-aligning to directortumbling, as evidenced by the appearance of a characteristic oscillatory stress response in startup flow and in flow reversal. The tumbling pattern of the mixture was very similar to that observed for pure 8CB, and, in agreement with theoretical prediction based on eqs 12 and 14, showed shear strain scaling of the oscillatory periodicity and the presence of characteristic doublet peaks. In direct contrast to the oscillatory behavior of 8CB and the MSHMA/5CB mixture, and again consistent with theoretical expectation, a single stress overshoot was observed for pure 5CB.

In this work, we investigate further aspects of the shear flow response of nematic monodomains containing LCPs. We demonstrate experimentally that the flow-aligning response of 5CB is changed gradually to director-tumbling behavior by a progressive increase of the side-chain LCP concentration. We also show for the first time that the director-tumbling character of 8CB can be suppressed by addition of sufficient quantities of a main-chain LCP. In addition, flow startup, flow reversal, and step flow studies are shown to support the existence of a unique director orientation profile at a specified shear strain. Results of the influence of temperature on the sign of α_3 are also presented. Finally, we carry out a numerical analysis of the periodicity, amplitude, and the shape of the stress response waveform to extract certain viscosity coefficients associated with director-tumbling and flow-aligning behaviors.

MSHMA
$$\begin{array}{c} CH_{3} \\ + CH_{2} - C \\ \hline C \\ \hline D \\ COO(CH_{2})_{6}O \end{array} \begin{array}{c} CH_{3} \\ \hline COO(CH_{2})_{15} \\ \hline \end{array}$$

$$\begin{array}{c} CH_{3} \\ \hline COO(CH_{2})_{15} \\ \hline \end{array}$$

5CB
$$CH_{3}$$
- $(CH_{2})_{4}$ CN 8CB CH_{3} - $(CH_{2})_{7}$ CN

Figure 2. Molecular structures of the liquid crystal polymers and nematic solvents used in this study.

2. Experimental Section

A Rheometrics RFS8500 fluid rheometer, equipped with a 10 g-cm transducer was used to perform the rheological measurements. To ensure a constant shear strain throughout the sample, a stainless steel cone and plate fixture (angle 0.02 rad; diameter 5 mm) was utilized as the sample cell. The sample thickness at the perimeter of the cell is 500 µm. The inner surfaces of the cone and plate assembly were treated with a 0.35% w/v solution of lecithin (Epikuron, Lucas Meyer Inc.) in ethanol to achieve surface anchoring for homeotropic alignment.³⁷ We independently verified that a uniform homeotropic monodomain can be obtained in a glass cell of thickness 600 µm using the same surface treatment. The sample temperature was controlled by a circulating thermal bath with temperature control accurate to within 0.1 °C. 8CB and 5CB were purchased from BDH Chemicals and used as received. A Carl Zeiss optical polarizing microscope, equipped with a Mettler FP82 hot stage and a Mettler FP800 central processor, was used to evaluate the miscibility of the LCP/LMMN mixtures and the phase transition temperatures for the materials. The nematic to isotropic transition temperatures T_{N-I} were determined to be 35.0 °C for 5CB and 39.8 °C for 8CB. The smectic A to nematic transition temperature $T_{\rm SmA-N}$ was found to be 33.3 °C for 8CB. The chemical structures of the LCPs used are shown in Figure 2. The side-chain LCP is poly-[6-(4-methoxy- α -methylstilbene-4'-yl)oxy]hexyl methacrylate] (MSHMA) and the main-chain LCP consists of mesogenic groups. 1-(4-hydroxy-4'-biphenyl)-2-(4-hydroxyphenyl) butane, separated by flexible spacers of 15 methylene units (TPB-15). Both sidechain and main-chain LCPs were synthesized by Professor Virgil Percec and co-workers and have been characterized previously. 38,39 MSHMA has a molecular weight of $M_n = 12\,000$ with $M_w/M_n =$ 1.35. TPB-15 has a molecular weight of $M_n = 30\,000$ with M_w $M_n = 2.12$. These two LCPs were found miscible with the nematic solvents 5CB and 8CB in the entire concentration range. 25,40 Our studies were performed over a concentration range of 0-4.5% w/w for MSHMA and 0-6.0% w/w for PBT-15. The mixtures have $T_{\rm N-I}$ in the range 0–2.0 °C higher than that of solvents and exhibit a narrow biphasic region (<3.0 °C) depending on concentration.

For observation of the transient response to shear flow, three different types of measurements were performed: (i) flow startup; (ii) step flow; (iii) flow reversal. In the flow startup measurements, the homeotropic monodomain in its rest state was subjected to a constant shear rate $\dot{\gamma}$ at time t=0, and the torque applied on the cone was measured to evaluate the average shear stress or, equivalently, the apparent viscosity of the sample. Since the measured torque must exceed 0.1% of the full scale of 10 g·cm to ensure an adequate signal-to-noise ratio, the lower limit of the shear rate permissible is about $4~\rm s^{-1}$ for the nematic solvents and about $1~\rm s^{-1}$ for the mixtures. The shear rate range in our experiments is located in the constant steady-state viscosity plateau region, as confirmed by steady shear rate sweep measurements; thus, the linear ELP theory is applicable. In the flow reversal measurements, the torque signal was recorded by an

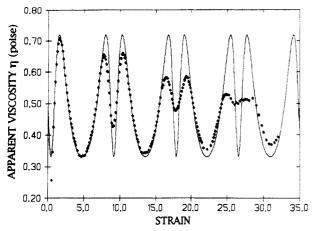


Figure 3. Comparison between theoretical calculation and experimental observation of director tumbling in transient shear flow of pure 8CB: (—) 2D linear ELP model neglecting elasticity; (•) measured result at $\Delta T = T_{\rm N-I} - T = 4.8$ °C and $\gamma = 16$ s⁻¹. The oscillation amplitude decays with strain, but the periodicity remains constant. Good agreement between calculation and experiment is found, up to approximately 8 strain units and with regard to the positions of the maxima and minima over the first five oscillations.

X-Y chart recorder through a cable output at the rear panel of the rheometer, while the rate sweep operation in steady shear mode was utilized in two shear directions. In the measurements of step flow, the specimen experiencing stress oscillation at a specified shear rate is suddenly subjected to a different shear rate while maintaining the direction of shear, and the shear stress is recorded as a function of time.

3. Results and Discussion

A. Transient Flow Behavior of MSHMA/5CB Mixtures. 8CB is a nematic material which has a positive α_3 over a major part of its nematic temperature range. Its viscoelastic properties have been well characterized, and thus it provides an ideal model system for rheological characterization of director-tumbling behavior. In Figure 3, we exhibit the transient response of this material to a simple shear flow in a cone and plate geometry. The apparent viscosity of 8CB is shown as a function of strain at $\Delta T = T_{N-I} - T = 4.8$ °C, together with a least-squares fit of the data to eqs 12 and 14. After the shear rate jumps from 0 to a constant value 16 s^{-1} at t = 0, the measured apparent viscosity shows several oscillations with an increase of strain. The peak-to-peak amplitude of the first oscillation, Δn , defined as the difference between the first maximum and the following minimum, is about 0.4 P. Since it is known that, at $\Delta T = 4.8$ °C, 8CB has $\alpha_3 >$ 0, these oscillations can certainly be related to the directortumbling phenomenon. From Figure 3, it is evident that the theoretical model based on eqs 12 and 14 fits the data rather well, except for the observed decrease of the tumbling amplitude with increasing strain. As discussed in more detail later, this damping effect may be due to several factors including out-of-plane motion of the director, the suppressive effect of the increasing elastic torque, and/or the appearance of polydomain structure. In Figure 3, it can be further seen that there is a small time lag of 30 ms, corresponding to about 0.5 strain unit, between time zero and the calculated first viscosity minimum. This time lag is due to a mechanical inertia effect, since the servo needs a finite period of time to accelerate to a constant shear rate. Details of the fitting procedure will be discussed later. Here we simply note that there are four viscosity coefficients involved in the fits: the Leslie coefficients α_1 , α_2 , and α_3 and the Miesowicz viscosity η_b . The twist viscosity γ_1 , that is, the quantity $\alpha_3 - \alpha_2$, was measured independently by dynamic light scattering from

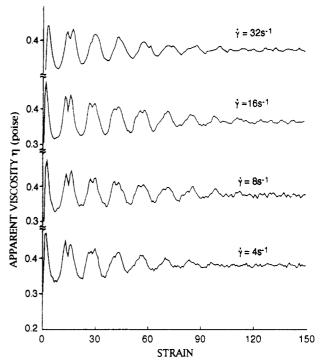


Figure 4. Director-tumbling behavior observed for 4.5% w/w MSHMA/5CB at different shear rates ($\Delta T = 10.0$ °C). The oscillation periodicity clearly shows a strain scaling law, and the existence of double-peak features similar to that for 8CB is evident in the initial oscillation cycles.

a homeotropic monodomain under application of an ac electric field.²⁶ Thus, there are only three independent parameters in the fitting procedure. The fitting values are $\gamma_1 = 0.60$ P, $\alpha_1 = 1.14$ P, $\alpha_2 = -0.51$ P, $\alpha_3 = 0.092$ P, and $\eta_b = 0.35$ P. These results agree very well with literature values for 8CB reported by Kneppe et al.^{32,41}

By dissolving a small amount of the side-chain LCP MSHMA into 5CB, the shear flow response of the nematic is changed from shear-aligning to director-tumbling. In Figure 4, the transient shear behavior of the MSHMA/ 5CB mixture at c = 4.5% w/w is shown at temperature T = 26.0 °C (ΔT = 10.0 °C) for four shear rates: $\dot{\gamma}$ = 4, 8, 16, and 32 s⁻¹. Evidently, the oscillatory stress response of the mixture is very similar to that observed for the director-tumbling LMMN, 8CB. There are two significant features of this oscillatory response worthy of mention here: one is that the strain periodicity of the oscillations remains at a constant value ($\gamma_p = 14.2 \pm 0.3$), not only at increasing strains but also for different shear rates, suggesting that the tumbling process scales with the shear strain in the shear rate range utilized in our experiments. The other feature is that, after η reaches the first minimum, a double peak always follows the minima of η for several oscillation cycles. These features are qualitatively consistent with the theoretical model which describes the tumbling transient flow behavior of 8CB. For the 4.5% w/w MSHMA/5CB mixture, the steady-state apparent viscosity, observed at sufficiently large strains, is 0.38 P. The initial oscillation amplitude is about 0.13 P, about 30% of the steady-state apparent viscosity. As observed for 8CB,37 the oscillation amplitude attenuates with the strain. We also found that, for consecutive applications of shear, the oscillation amplitude depends on the rest time, which is defined as the time interval between cessation and reapplication of shear. The recovery process exhibits an exponential time dependence, and, typically, the mixture takes about 10-15 min to revert back to the original homeotropic orientation.³⁷ An estimation of the size L of the flow-induced structure can be made from the relation $L = (Kt/\eta)^{1/2}$, where K is the appropriate elastic

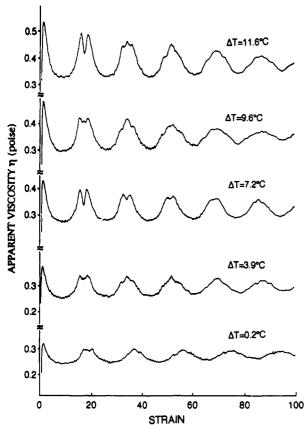


Figure 5. Director-tumbling behavior observed for 3.05% w/w MSHMA/5CB at various temperatures in the nematic state (γ = 16 s⁻¹). The tumbling amplitude decreases with a decrease of ΔT , but the oscillation periodicity remains constant except when T_{N-1} is approached. The double-peak feature is discernable only in the initial cycles.

constant, η is the corresponding viscosity coefficient, and t is the recovery time.⁴² Using typical values, $K = 5.0 \times$ 10^{-7} dyn, $\eta = 0.5$ P, and t = 900 s, we find $L = 300 \mu m$, which is in reasonable agreement with the maximum sample thickness of 500 μ m at the cone edge.

When the MSHMA/5CB mixture is diluted to 3.05% w/w and 1.84% w/w concentrations, the tumbling phenomenon is still present. Figure 5 shows the transient shear response of 3.05% w/w MSHMA/5CB at different temperatures in the nematic state ($\gamma = 16 \text{ s}^{-1}$). The tumbling amplitude decreases with an increase of temperature, but the oscillation periodicity remains at a constant value $\gamma_p = 17.5 \pm 0.5$, although a slightly longer $\gamma_p = 19.0 \pm 0.6$ is observed at a temperature only 0.2 °C below the nematic to isotropic transition temperature. It has been shown that one oscillation cycle corresponds to a director rotation angle of π and the corresponding strain periodicity is⁴³

$$\gamma_{\rm p} = \frac{\pi (1 + \delta^2)}{\delta} \tag{17}$$

where $\delta = (-\alpha_3/\alpha_2)^{0.5}$. According to eq 17, the periodicity depends only on the ratio of α_3 and α_2 . The constant periodicity in the tumbling behavior of 3.05% MSHMA/ 5CB indicates that, at this particular concentration, the increments of α_3 and α_2 due to addition of MSHMA ensure that the ratio of α_3 and α_2 of the mixture remains constant with temperature.

A quite different situation is seen for the 1.84% w/w MSHMA mixture as shown in Figure 6. Here the doublet peak disappears, the oscillation periodicity increases substantially with a decrease of ΔT , the oscillation amplitude decreases with a decrease of ΔT , and finally, near $\Delta T = 4.1$ °C, the mixture becomes a flow-aligning

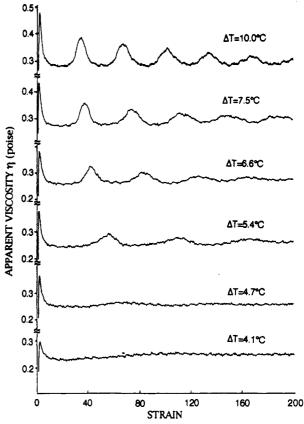


Figure 6. Transient shear response recorded for 1.84% w/w MSHMA/5CB ($\dot{\gamma} = 16 \text{ s}^{-1}$). The apparent viscosity is plotted as function of strain at different temperatures. A crossover between director tumbling and shear aligning is found between $\Delta T = 4.7$ and 4.1 °C. The nematic mixture shows tumbling behavior at temperatures below the crossover point and flow-aligning behavior above this crossover point. The tumbling amplitude decreases, and the periodicity increases, with decrease of ΔT .

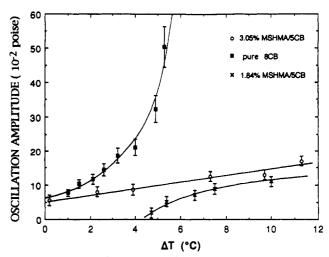


Figure 7. Dependence of tumbling amplitude shown as a function of ΔT for the MSHMA/5CB mixture at two concentrations and compared with that of pure 8CB ($\dot{\gamma}$ = 16 s⁻¹). The tumbling of 8CB has a stronger ΔT dependence and shows a divergence in amplitude near the smectic to nematic transition.

nematic. It is interesting to compare the temperature dependence of the oscillation amplitude of the MSHMA/ 5CB mixture to that of pure 8CB. In Figure 7, the peakto-peak amplitude of the first oscillation in apparent viscosity $\Delta \eta$ is plotted against ΔT for 3.05% w/w and 1.84% w/w MSHMA/5CB and for 8CB. The oscillation amplitude of the mixture increases only slightly with an increase of ΔT , whereas the oscillation amplitude of 8CB shows a strong dependence on temperature and diverges when the temperature approaches the nematic to smectic transition. This divergence can be understood by considering the

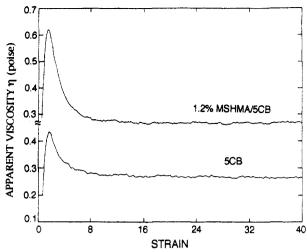


Figure 8. At 1.20% w/w concentration, MSHMA/5CB appearing as a flow-aligning nematic over its entire nematic temperature range ($\gamma = 16 \text{ s}^{-1}$). Its transient shear flow response is similar to that of pure 5CB. A shear stress overshoot appears at a shear strain of about 1, and a steady state is reached after 10 strain units

dependence of the oscillation amplitude on the related viscosity coefficients of 8CB. Setting $\theta=0$ and $\pi/4$ in eq 12 and taking the difference between the two calculated values, we have

$$\Delta \eta = \frac{\alpha_1}{4} + \frac{(\alpha_2 + \alpha_3)^2}{4(\alpha_3 - \alpha_2)} \tag{18}$$

It has been previously reported that, for 8CB, both α_1 and α_3 diverge as the temperature approaches T_{S-N} . Thus, based on eq 18, the oscillation amplitude in the apparent viscosity must also diverge near T_{S-N} . For the MSHMA/ 5CB mixtures, no such divergence was found, since the mixtures do not have a smectic phase. From eq 18, an approximate estimation of $\Delta \eta$ can be made. Because the polymer concentration is very low, the magnitude of the change in the viscosity coefficients appearing in eq 18 is small and can be neglected. It then follows that α_2 is the dominant factor which contributes to $\Delta \eta$, since it is about 1 order larger than α_1 and α_3 for 5CB.⁴⁴ We may therefore write $\Delta \eta \approx -\alpha_2/4$, where α_2 is the solvent value. Comparing the measured value of $\Delta \eta$ (~0.20 P) in the tumbling response of a 3.05 % w/w MSHMA/5CB mixture, as shown in Figure 7, to the value of α_2 (~ 0.84 P) for 5CB reported by Skarp et al. at $\Delta T = 10$ °C, ⁴⁴ good agreement is found. When the MSHMA/5CB mixture was further diluted to a concentration of 1.20% w/w, the sample exhibits transient shear flow behavior characteristic of a flowaligning nematic at all temperatures in the nematic state. In Figure 8, the apparent viscosity of 1.20% w/w MSHMA/ 5CB is compared with that of pure 5CB at a shear rate of 16 s⁻¹, and $\Delta T = 10.0$ °C, deep in the nematic state. It is clear that no oscillatory response is present. Instead, as for pure 5CB, a single stress overshoot peak appears, following the inception of flow. This flow-aligning behavior of the mixture indicates that the MSHMA concentration of 1.20% w/w is below the concentration threshold required to switch the sign of α_3 and induce director tumbling in the mixture over the entire nematic temperature range.

To provide further support that the stress oscillations observed in the transient response of the mixture to simple shear are not due to some unknown instability but are due to director tumbling, step flow experiments were performed on a 3.05% w/w MSHMA/5CB solution. If the director orientation profile or the director rotation angle is a unique function of shear strain, as predicted by the theoretical model, then a sudden change of the shear rate

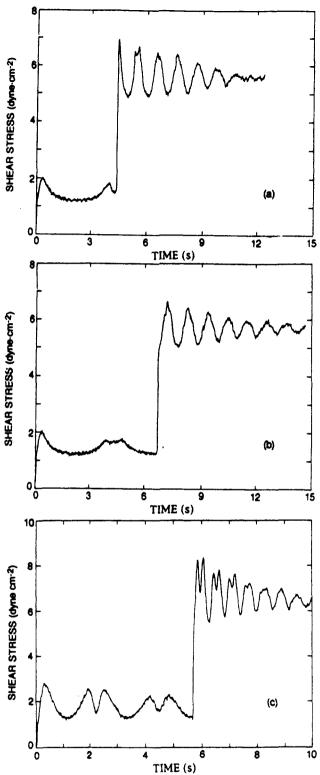


Figure 9. Transient stress response to step-up flow (a change in shear rate γ from 4 to $16\,\mathrm{s}^{-1}$) compared for 3.05% w/w MSHMA/5CB ($\Delta T = 10.0\,^{\circ}$ C) and for 8CB ($\Delta T = 4.8\,^{\circ}$ C): (a) for MSHMA/5CB, the shear rate is stepped at t = 4.40 s, corresponding to director orientation angle $\theta = \pi$. (b) For MSHMA/5CB, the shear rate is stepped at $t = 6.60\,\mathrm{s}$, corresponding to $\theta = 3\pi/2$. (c) For 8CB, the shear rate is stepped at $t = 6.66\,\mathrm{s}$, corresponding to $\theta = 5\pi/2$

to a different constant value at any moment during the oscillation should not disrupt the director orientation profile and the coherent strain scaling of the variation in the apparent viscosity. The results are shown in Figure 9 in the form of shear stress plotted against time. In Figure 9a, at t = 4.40 s, the shear rate is changed from 4 to 16 s⁻¹. The strain at which the shear rate is changed corresponds to a director rotation angle of π ; i.e., the director is oriented

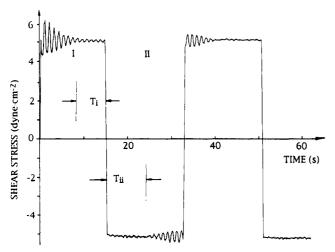


Figure 10. Transient stress response to flow reversal for 3.05% w/w MSHMA/5CB at $\Delta T = 10.0$ °C ($\dot{\gamma} = 16$ s⁻¹). The switching of the flow direction occurs at t = 15, 33, and 51 s. There is a time interval $T_{\rm II}$ between the inception of flow reversal and the reappearance of the stress oscillation.

perpendicular to the flow. It is clearly evident that the director-tumbling process is continuous: a single peak, whose width is half that of the following oscillation, is seen immediately following the stepping-up of the shear rate, as if the system is undergoing a flow startup with the director initially aligned perpendicular to the flow; the time periodicity of the oscillation becomes 3 times shorter because of the strain scaling of the tumbling process. In Figure 9b, the shear rate is changed from 4 to 16 s⁻¹ at t= 6.60 s which corresponds to a director rotation angle of $3\pi/2$. The initial narrow peak feature appearing in Figure 9a is not seen here. Instead, a series of oscillations of comparable width follows the stepping-up in shear rate, with the time periodicity about a quarter that of the initial oscillations. Strictly, we should expect to see a doublet peak immediately following the step jump and beyond. The inability to resolve the doublet peak feature in parts a and b of Figure 9 is due to the very small values of α_3 . For illustration, the response to step flow for pure 8CB at $\Delta T = 5.1$ °C is given in Figure 9c. The shear rate was stepped from 4 to 16 s⁻¹ at t = 5.67 s, corresponding to θ = $5\pi/2$. As evident in Figure 9c, pure 8CB which has a larger α_3 shows very clearly that the details of the oscillatory pattern are maintained, following the step in shear rate.

For further insight, we carried out flow reversal experiments, in which the sample is subjected to a sudden reversal of the flow direction, at a constant shear rate. Figure 10 exhibits the oscillatory response to the switching of flow direction for 3.05% w/w MSHMA/5CB ($\Delta T = 10.0$ °C). The behavior we see here is similar to that which we have earlier reported for 4.5% w/w MSHMA/5CB.37 After flow direction is altered, the stress oscillations do not appear immediately, but after a time interval $T_{\rm II}$, defined as the time between the flow reversal event and the initial reappearance of the stress oscillation in time zone II. $T_{\rm II}$ is comparable to the time interval T_I between the disappearance of the previous oscillation pattern in time zone I and the flow reversal event. If flow reversal is imposed during stress oscillation, the oscillation continues immediately after the flow reversal.³⁸ The reappearance of the stress oscillation, which is observed when the total strain is not too large,37 is qualitatively consistent with the idea that the director configuration is going through a process analogous to "winding" and "unwinding"

Our experimental results demonstrate that the dissolution of a side-chain LCP MSHMA in a flow-aligning nematic solvent 5CB induces a director-tumbling response

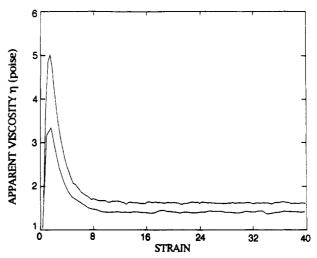


Figure 11. Transient response to flow startup for 4.05% w/w TPB-15/8CB at $\Delta T = 6.0$ °C and $\gamma = 8 \, \text{s}^{-1}$ (lower curve) and for 6.0% w/w TPB-15/5CB at $\Delta T = 10.0$ °C and $\gamma = 8 \, \text{s}^{-1}$ (upper curve), plotted as the apparent viscosity against strain. A single stress overshoot appears, characteristic of a flow-aligning nematic. Note that the stress overshoot amplitudes and the steady viscosities are much higher than those for pure 5CB (Figure 8).

to shear flow. The oscillatory transient wave forms of the nematic mixture recorded in flow startup, step flow, and flow reversal experiments are very similar to those observed for the tumbling low molar mass nematic 8CB.37 The tumbling dynamics follows a strain scaling law and is concentration dependent. The strain periodicity of the oscillation decreases with increasing polymer concentration. The oscillation amplitude decreases on dilution of the mixture. At 1.20% w/w concentration, the directortumbling behavior disappears and the mixture becomes flow-aligning again. Temperature also influences the transient response of the mixture by changing the oscillation amplitude and periodicity. A crossover between director tumbling and flow aligning was observed in the 1.84% w/w mixture between $\Delta T = 4.7$ and 4.1 °C. The change in sign of α_3 upon addition of a small amount of MSHMA to 5CB is consistent with the hydrodynamic theory of Brochard.²⁴ If the backbone of the dissolved polymer has an oblate configuration $(R_{\perp} > R_{\parallel})$ in the nematic solvent, according to eqs 4 and 5, the increments of the Leslie viscosity coefficients α_2 and α_3 are both positive. When the concentration is high enough, the positive increment of α_3 becomes larger than the negative α_3 of the solvent 5CB and a transition from flow-aligning to director-tumbling is predicted.

B. Transient Flow Behavior of Main-Chain LCP Mixtures. Brochard's theory²⁴ further indicates, via eqs 4 and 5, that, if a LCP chain takes up a prolate configuration in a nematic solvent, the increments of α_2 and α_3 will each be negative. Therefore, dissolution of such a polymer into a director-tumbling nematic solvent should suppress the oscillatory response of the material at a sufficient concentration. Miscible mixtures of the main-chain LCP, TPB-15, in 8CB provide a vehicle to test this prediction. In Figure 11, the transient flow startup response of a 4.08% w/w TPB-15/8CB is shown as the apparent viscosity plotted against strain at $\Delta T = 6.0$ °C and $\gamma = 8 \,\mathrm{s}^{-1}$, together with the flow behavior of the miscible mixture of the main-chain LCP TPB-15 (6.00% w/w) in 5CB ($\Delta T = 10.0$ °C and $\gamma = 8$ s⁻¹). In each mixture, only a single peak appears immediately after the flow startup, typical of the stress overshoot in a flow-aligning nematic. It is therefore clear that the director-tumbling character of 8CB has been completely suppressed by the addition of the main-chain LCP. The amplitude of the overshoot of TPB-15/8CB, $\Delta \eta$, is 2.0 P, much higher than that of the

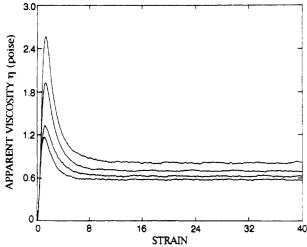


Figure 12. Transient response to flow startup for 2.0% w/w TPB-15/8CB at different temperatures ($\Delta T = 1.5$, 3.8, 5.4, and 6.4 °C, $\gamma = 16$ s⁻¹). With an increase of ΔT , both the overshoot amplitude and the steady viscosity increase systematically, though the flow-aligning character of the mixture does not change.

1.20% w/w side-chain LCP mixture and pure 5CB (Figure 8). The steady-state viscosity is 1.4 P, again much higher than that of the 1.20% w/w side-chain LCP mixture and pure 5CB. A single stress overshoot peak, similar to that observed for the 4.08% w/w TPB-15/8CB mixture, was also found for the 6.0% w/w TPB-15/5CB mixture. The amplitude $\Delta\eta$ is about 3.4 P and the steady apparent viscosity is 1.6 P, in each case somewhat higher than the corresponding values for 4.08% w/w TPB-15/8CB, reflecting the higher TPB-15 concentration.

Upon dilution of the TPB-15/8CB mixture to 2.00% w/w concentration, there was still no evidence for director tumbling in the transient response function, as shown in Figure 12. Here, the apparent viscosity of the mixture is plotted as a function of strain for different temperatures in the nematic state. Evidently, both the amplitude of the stress overshoot and the steady apparent viscosity increase with an increase of ΔT . The increment of the steady apparent viscosity of this 2.00% w/w mixture is about 4 times larger than that of the 3.05 % w/w MSHMA/ 5CB, indicating that the effective hydrodynamic volume of the main-chain LCP is larger than that of the sidechain LCP. Efforts will be made in the following section to quantitatively relate the shape of the transient response function to specific viscosity coefficients of the mixtures. When the polymer concentration is further diluted to 0.48% w/w in 8CB, an interesting temperature-dependent crossover between tumbling and flow-aligning behavior is found, analogous to that observed in the 1.84% w/w sidechain LCP/5CB mixture, as shown in Figure 13. At ΔT = 6.0 °C, the mixture clearly exhibits director-tumbling, as evidenced by the presence of the characteristic oscillations, including doublet peaks, in the transient shear response. The initial oscillation amplitude is comparatively large: $\Delta \eta = 1.3$ P, indicating that the mixture is near T_{S-N} , at which $\Delta \eta$ diverges as seen in Figure 7 for pure 8CB. When ΔT decreases to 5.2 °C, more oscillatory cycles are seen, and the oscillation periodicity doubles compared with that at $\Delta T = 6.0$ °C. When ΔT is decreased further to 4.4 °C, the oscillation periodicity becomes 4 times longer than that at $\Delta T = 6.0$ °C. The crossover between tumbling and flow-aligning occurs between ΔT = 4.4 and 4.0 °C as the oscillation has totally disappeared at the latter temperature. At $\Delta T < 4.0$ °C, the mixture shows flow-aligning behavior.

Our rheological investigation of the TPB-15/8CB mixture indicates that dissolution of a sufficient quantity of

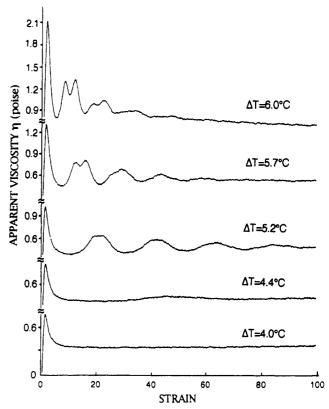


Figure 13. Crossover between director-tumbling and flow-aligning when TPB-15/8CB is diluted to a concentration of 0.48% w/w. At $\Delta T > 4.0$ °C, the mixture shows tumbling behavior; at $\Delta T \leq 4.0$ °C, a single stress overshoot is evident, characteristic of a flow-aligning nematic ($\dot{\gamma} = 16 \text{ s}^{-1}$).

a main-chain LCP in a director-tumbling nematic solvent can indeed suppress the tumbling behavior and convert the mixture into a flow-aligning nematic. The increase of the apparent viscosity is much larger than those due to the addition of a side-chain LCP MSHMA into 5CB. A crossover between director-tumbling and flow-aligning is found between $\Delta T = 4.4$ and 4.0 °C at concentration c = 0.48% w/w.

C. Quantitative Analysis of the Transient Shear Response of LCP/LMMN Mixtures. Clearly the oscillatory waveforms in the director-tumbling response which we observe for the LCP/LMMN nematic mixtures are highly structured. The question naturally arises as to whether these waveforms can be quantitatively analyzed in terms of the linear ELP hydrodynamic theory embodied in eqs 12, 14, and 15. The oscillatory responses observed in our studies have a higher information content than those reported for lyotropic liquid crystal polymer solutions and thermotropic liquid crystal polymer melts.⁸⁻¹⁹ As noted earlier, our results contain features which are indeed very similar to those predicted by the linear ELP theory for simple shear deformation of a homeotropic monodomain of 8CB. In particular, the "doublet peak" characteristic appears in the numerical prediction of the transient response to shear flow of 8CB at high Erickson numbers under director-tumbling conditions.²⁰ The doublet arises directly from the difference in the absolute values of α_2 and α_3 . As indicated by eqs 13 and 14, the director rotation speed is dominated by α_2 when the director is near the vertical position ($\theta = n\pi$) and is dominated by α_3 when the director is near the horizontal positions ($\theta = m\pi/2$, m =odd). A small α_3 value means that the director spends a longer time passing through the horizontal position. Thus the shear stress maxima corresponding to $\theta = \pm m\pi/4$ (m = odd) occur relatively close to the strain locations which correspond to vertical positions of the director, and the

doublet peak effect appears. When $\alpha_2 = -\alpha_3$ the director rotation speed is essentially constant and a singlefrequency oscillation should be observed. This has been experimentally confirmed by us in a study of the transient shear response of pure 8CB near its smectic to nematic transition where $\alpha_2 \approx -\alpha_3$.⁴⁵ According to eq 12, the oscillation amplitude $\Delta \eta$ depends on the viscosity coefficients α_1 , α_2 , and α_3 , and the time-averaged viscosity depends on the viscosity coefficients η_b , α_2 , and α_3 . Thus we can determine these coefficients by appropriate analysis of the experimental data.

Efforts of this kind were made by Yang and Shine¹⁷ to estimate the Leslie viscosity coefficients for a lyotropic poly(n-hexyl isocyanate) (PHIC) solution. However, in their study, the fitting was limited to the first oscillation peak because of a lack of subsequent oscillation cycles. 17 We note that a parallel-plate sample fixture was used in their experiments which may lead to destructive interference between stress oscillations with different strain scaling frequencies. In our investigation, a unique shear rate is specified by the angular velocity of the plate relative to the cone. The dimensionless velocity V_0 is then the Erickson number:²⁰

$$E_{\rm r} = V_0 = v_0 |\alpha_2| d/K_{11} \tag{19}$$

where v_0 is the velocity of the moving plate, d the sample thickness, and K_{11} the splay elastic constant. In the analysis of Burghardt and Fuller,20 the presence of the doublet peak is evident when E_r is larger than 300. In our experimental geometry, E_r is proportional to the square of the radial distance r in the sample from the center of the cone. If the angular velocity is chosen as 0.16 rad s⁻¹ corresponding to a shear rate of 8 s⁻¹ for 8CB at $\Delta T = 3$ °C, using literature values of α_2^{44} and K_{11} , 46 the Erickson number E_r varies typically from 325 to 32 500, as the sample thickness increases from 50 μ m at the center to 500 μ m at the edge of the cone/plate. Considering the dominant contribution of the shear stress from the edge region to the torque (torque $d\Gamma \propto r^2 dr$), the effective value of V_0 is around 10⁴ in our experiments. Furthermore, in the cone and plate arrangement, the macroscopic strain is constant, at a given shear rate, throughout the entire sample volume. Therefore, an extended oscillatory response and the presence of the doublet peak features is clearly to be expected. Since the cone angle is very small $(\beta = 1.15^{\circ})$ and the sample thickness is much larger than the coherence length over which the surface anchoring influence is effective, a homeotropic orientation condition remains a good approximation. The observed strain scaling in the oscillation periodicity and the continuity of the stress waveform in step flow are clear confirmation that the peaks and valleys in the stress oscillation correspond to particular director orientation angles. In our observations, however, while the periodicity of the oscillation remains constant, the amplitude of the oscillation decays to zero with an increase of strain. Apparently, the director rotates with a constant mean angular velocity until the tumbling amplitude decays to zero.

As noted earlier, a possible mechanism which leads to this attenuation is the increase of elastic torque due to the continual "winding up" of the director orientation profiles. With increasing rotation, the director orientation profile becomes more distorted and there will be a gradual increase in the nematic elastic energy until the oscillation in the shear stress attenuates to zero. However, if the shear rate is high enough, the elastic suppression of the tumbling is not severe in the first few oscillation cycles. Thus a numerical curve-fitting procedure which involves only the hydrodynamic torques can be utilized, in principle, to extract the pertinent viscosity coefficients. Indeed, the

success of such an analysis is demonstrated in Figure 3, for pure 8CB, for which these viscosities are known. For flow-aligning nematics, the neglect of elasticity is safer, since the increase in the elastic distortion energy can occur only within the initial few strain units where it should be negligible. Additionally, we pointed out that, in the ELP model, the director is assumed to be always located in the shear plane. This is a potential oversimplification because there is a distinct possibility that the director may go out of the shear plane. 33,34 Theoretical analysis by Burghardt 47 indicates that the oscillation amplitude attenuates and that the depth of the minima at $\theta = m\pi/2$ (m is odd) diminishes relative to those at $\theta = n\pi$, leading to a gradual disappearance of the doublet peak as the director moves out off the shear plane. Importantly, however, the oscillation periodicity remains constant.⁴⁷ This behavior is quite consistent with the changes observed in our experiments as the strain increases (Figure 3). Our flow reversal experiments indicate that, in the cone/plate geometry, if the director moves out of the shear plane, a switch in the flow direction is able to bring it back toward the shear plane again. However, in our previous study³⁷ of flow reversal in 4.5% w/w MSHMA/5CB, we found that, if the sample is sheared too long (at least 3 times longer than the time duration of the oscillatory response), then the stress oscillation does not reappear after flow reversal. Apparently, a critical value of the total strain exists. When this value is exceeded, flow reversal does not lead to tumbling. This indicates that an out-of-plane process may indeed occur, but with a time scale which is much longer than that of the tumbling phenomenon. The presence of a polydomain texture is another possible factor which may influence the tumbling amplitude, since the magnitude of the oscillation diminishes in the polydomain case, as noted by Yang and Shine. 17 To gain more detailed insight into director dynamics during shear deformation, we need to resort to additional experimental techniques such as rheooptical measurements.

In numerical curve fitting of the transient response, four independent viscosity coefficients appear in eq 12. We find that one of these coefficients, specifically from α_1, α_2 , and α_3 , must be independently measured in order to obtain an unambiguous solution. Therefore, using dynamic light scattering with application of an ac electric field,26 we measured $\gamma_1 = \alpha_3 - \alpha_2$ for the LCP mixtures. Shown in Figure 14 are the twist viscosities of 3.05% w/w MSHMA/ 5CB and 2.0% w/w TPB-15/8CB, together with those of 5CB and 8CB, plotted as a function of temperature. The main-chain LCP shows a much larger viscosity increase than the side-chain LCP, despite having a lower concentration. Using a least-squares algorithm in a threeparameter fitting to eqs 12, 14, and 15, we then obtained α_1 , α_2 , α_3 , and η_b for both director-tumbling and flowaligning LCP mixtures. In Figures 15 and 16, examples are given for the curve fits to the tumbling response of 3.05% w/w and 1.84% w/w MSHMA/5CB mixtures, at $\Delta T = 7.5$ °C, and to the flow-aligning response of 2.0% w/w TPB-15/8CB at $\Delta T = 6.4$ °C. The increments in the viscosity coefficients associated with these fittings are listed in Table 1.

According to Figure 15, when the LCP concentration is reduced from 3.05% w/w to 1.84% w/w, the oscillation periodicity is doubled and the double-peak feature disappears. The curvature near the strain region which corresponds to $\theta = \pi/2$ becomes flatter, indicating a smaller hydrodynamic torque is experienced by the director and a slower director rotation speed. The most sensitive parameter in the fitting is the ratio $\delta = -\alpha_3/\alpha_2$ which determines the strain periodicity of the oscillations. The precision in the calculated viscosity coefficients is deter-

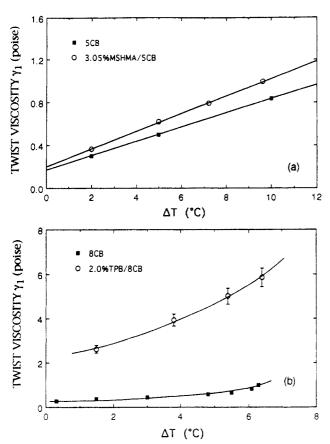


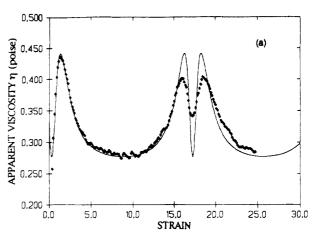
Figure 14. Results of dynamic light scattering under application of an ac electric field shown for MSHMA/5CB and TPB-15/8CB. The twist viscosities of the mixture are compared with those of the solvents at different temperatures. A comparatively high viscosity increase is produced in the case of the main-chain LCP TPB-15.

Table 1. Viscosity Parameters for LCP Mixtures (P)

.,,	3.05% MSHMA/5CB	1.84% MSHMA/5CB	2.0 % TPB-15/8CB
$\Delta \alpha_1$	0.06 ± 0.03	0.06 ± 0.03	-1.24 ± 0.15
$\Delta \alpha_2$	-0.113 ± 0.04	-0.062 ± 0.04	-5.27 ± 0.30
$\Delta \alpha_3$	0.067 ± 0.002	0.044 ± 0.002	-0.40 ± 0.03
$\Delta \gamma_1$	0.180 ± 0.04	0.106 ± 0.04	4.87 ± 0.30
$\Delta\eta_{ m b}$	0.058 ± 0.04	0.048 ± 0.04	0.074 ± 0.08
$\Delta \gamma_1/\Delta \alpha_3$	2.7 ± 0.7	2.4 ± 1.0	-12.2 ± 1.6
$\Delta \alpha_3/\Delta \eta_b$	1.2 ± 0.9	0.9 ± 0.8	-5.4 ± 5.9

mined by fitting data up to the leading edge of the second oscillation peak. In Figures 15 and 16, the initial minima of the calculated viscosities do not appear at time zero. As noted earlier, this delay in instrument response arises from the inertia of the rheometer servo and does not contribute significantly to the fitting errors, since it can be corrected by a zero-time shift. The uncertainties in Table 1 for most viscosity increments are comparatively large since they reflect the differences between values for the mixtures and solvents.

Bearing in mind the large uncertainties in Table 1, a comparison can be made between the measured viscosity increments and the predictions of the Brochard model. First, the increments in α_3 for the solutions, induced by addition of only a few percent of LCP, are larger in magnitude and of opposite sign to the α_3 values of the corresponding solvents. This reflects the dramatic changes, demonstrated in this work, in the transient shear responses for the LCP mixtures compared to the solvents. According to Brochard, 24 via eq 5, anisotropic polymer chain configurations must be present in order to have such changes in the sign of α_3 . Specifically, $R_{\perp} > R_{\parallel}$ for the side-chain LCP MSHMA, and $R_{\perp} < R_{\parallel}$ for the main-chain



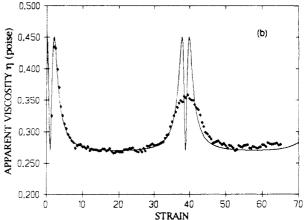


Figure 15. Comparison between theoretical fits and experimental results on the oscillatory tumbling response shown for MSHMA/5CB at concentrations of (a) 3.05% w/w ($\dot{\gamma}$ = 16 s⁻¹, ΔT = 7.2 °C) and (b) 1.84% w/w ($\dot{\gamma}$ = 16 s⁻¹, ΔT = 7.5 °C). The periodicity becomes longer, and the double peak in the experimental data disappears at the lower concentration. The accuracy of the fit is good at smaller strains γ < 15 in a and γ < 35 in b.

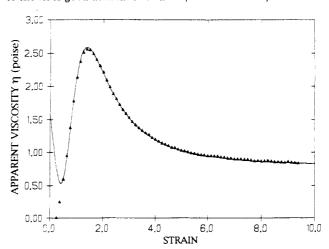


Figure 16. Theoretical fits and experimental results on the flow-aligning response of 2.0% w/w TPB-15/8CB at ΔT = 6.4 °C and γ = 16 s⁻¹.

LCP TPB-15. This is qualitatively in accord with the results of our earlier light scattering experiments.^{25–27} Second, according to eqs 1, 3, and 5, we may write

$$A_{\rm r} = \frac{\Delta \gamma_1}{\Delta \alpha_3} = \frac{\Delta \alpha_3}{\Delta \eta_{\rm b}} = \frac{R_{\perp}^2 - R_{\parallel}^2}{R_{\perp}^2} \tag{20}$$

From Table 1, we have $A_{\rm r} < 0$ for the main-chain LCP mixture, consistent with the prolate condition $R_{\perp} < R_{\parallel}$. Using the more precise estimate based on $\Delta \gamma_1/\Delta \alpha_3$, for the main-chain LCP TPB-15, $R_{\perp}/R_{\parallel} \approx 0.28$. The picture for

the side-chain LCP mixtures in Table 1 is not so clear due to the relatively large uncertainties. In fact, for side-chain LCP mixtures, the observations that $\Delta \alpha_2 < 0$ and $\Delta \gamma_1 / \Delta \alpha_3$ > 1, beyond any experimental uncertainty, are fundamentally inconsistent with the Brochard prediction, as can be seen by comparing egs 4 and 20. If the side-chain LCP core is indeed oblate, $\Delta \alpha_2$ should be positive. This suggests that an improved theoretical description is required when the chain anisotropy is small.

The curve-fitting results indicate that by using the 2D linear ELP description, the viscosity coefficients α_1 , α_2 , α_3 , and η_b can be extracted with reasonable precision from the transient shear responses of both director-tumbling and shear-aligning nematics, provided an independent determination of the twist viscosity is made. The ratio of the increments of Leslie coefficients $\Delta \alpha_3/\Delta \alpha_2$ can be unambiguously and precisely measured in the directortumbling case. Brochard's theory qualitatively explains the change in sign of α_3 upon dissolution of LCPs in nematic solvents but appears to need further refinement in order to quantitatively describe the phenomenon.

4. Conclusion

We examined the transient shear flow responses of nematic monodomains containing two LCPs with different architectures. The addition of a side-chain LCP MSHMA to an originally flow-aligning nematic (5CB) induces director-tumbling responses in flow startup, step flow, and flow reversal. In contrast, dissolution of a main-chain LCP (TPB-15) in a director-tumbling nematic solvent 8CB suppresses the tumbling behavior of the mixture. Directortumbling LCP mixtures show a characteristic oscillatory response which scales and decays with shear strain, similar to the rheological behavior of pure 8CB, whereas a single stress overshoot is present in the shear response of flowaligning LCP mixtures, as also observed in pure 5CB. With a change in the sample temperature, a crossover between director-tumbling and flow-aligning was found at certain LCP concentrations for both side-chain and main-chain LCP mixtures. Using the 2D model based on linear ELP theory, the transient responses of both tumbling and aligning systems were numerically analyzed to extract the associated viscosity coefficients. For pure 8CB, the curvefitting results are consistent with the literature values. The switch in sign of the Leslie coefficient α_3 , that is, the distinct rheological behavior of the solutions relative to that of the solvents, can be qualitatively explained by Brochard's theory, provided that an oblate configuration in the polymer backbone is present for side-chain LCP MSHMA in 5CB and a prolate configuration exists for the main-chain LCP TPB-15 in 8CB.

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